

# Motivation

- Automatic speech recognition (ASR) systems suffer from several adversarial voice attacks.
- Prior work [1] focus on the distinction of voice using the frequency and noise features.
- For driverless vehicle application, we want to find more robust features through the physical attributes of the received signals because of the fixed voice source locations.
- By using a pair of close-coupled microphones, we developed a secure ASR system (SASR) which contains three detection steps.



Location and Orientation of a Dual Microphone

## References

[1] M. Zhou, Z. Qin, X. Lin, S. Hu, Q. Wang, and K. Ren. 2019. Hidden Voice Commands: Attacks and Defenses on the VCS of Autonomous Driving Cars. IEEE Wireless Communications (2019), 1–6.

[2] Jes ús Villalba and Eduardo Lleida. 2011. Detecting Replay Attacks from Far-Field Recordings on Speaker Verification Systems. In Biometrics and ID Management, Springer Berlin Heidelberg, Berlin, Heidelberg, 274–285.

Shu Wang, Kun Sun {swang47, ksun3}@gmu.edu







via time difference of arrivals (TDOA).

### **Detecting Voice from Mobile Phone**

We distinguish the replay attacks through frequency-domain power spectrum due the low-frequency energy loss of mobi speakers [2].

To prevent the modulated voice which ca compensates the energy loss in frequence domain, we develop a time-domain doub granularity extrema cross-check approach.



is 83.3%, 96.8%, 97.6% respectively.

Detection Step	Running Time	Men
Multi-speaker Detection	134 ms	111
Single Source Identification	33 ms	23
Mobile Replay Detection	47 ms	10
Total Overhead Costs	214 ms	144
	A CONTRACTOR	• <b>L</b> ( <sub>1</sub>
Artificia	al Intelligend	ce a
Cyberse	ecunity Wo	rksl
June 4-6. 20	019 I University c	of Mar

